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• Lorentz's force equation:

$$\vec{F} = q \left(\vec{E} + \vec{u} \times \vec{B} \right)$$



Introduction-2

- Historically, \vec{B} is defined by measuring \vec{u} and \vec{F}_m experimentally.
- We will start with two fundamental postulates to define \vec{B} .
- Derive all experimental laws and the concept of vector magnetic potential.

Outline

- Fundamental postulates
- Ampere's circuital law
- Vector magnetic potential
- Biot-Savart law
- Magnetic dipole



2. Integral forms

Definition

Helmholtz's theorem: \vec{B} can be uniquely defined by specifying its divergence and curl:

$$\nabla \cdot \vec{B} = 0$$
$$\nabla \times \vec{B} = \mu_0 \vec{J}$$

permeability of

vacuum

Physical meanings

$$\nabla \cdot \vec{B} = 0$$
 ... no flow source

$$\nabla \times \vec{B} = \mu_0 \vec{J} \dots \vec{J}$$
 acts as vortex source

Integral form-1

$$\begin{cases} \nabla \cdot \vec{B} = 0 \\ \oint_{S} \vec{A} \cdot d\vec{s} = \int_{V} (\nabla \cdot \vec{A}) dv \end{cases} \longrightarrow \begin{bmatrix} \oint_{S} \vec{B} \cdot d\vec{s} = 0 \\ \end{bmatrix}$$

The magnetic flux lines always close upon themselves, there is no isolated "magnetic pole". Integral form-2

$$\begin{cases} \nabla \times \vec{B} = \mu_0 \vec{J} \\ \oint_C \vec{A} \cdot d\vec{l} = \int_S (\nabla \times \vec{A}) \cdot d\vec{s} & \longrightarrow & \oint_C \vec{B} \cdot d\vec{l} = \mu_0 I \\ & \text{Ampere's circuital law} \end{cases}$$

The counterpart of *Gauss's law* $\oint_{s} \vec{E} \cdot d\vec{s} = Q/\varepsilon_{0}$ in magnetostatics, relating the source (current *I*) and field (\vec{B}).



2. Examples

Definition

If the current distribution has certain symmetry, s.t. the tangential component of \overline{B} is constant over a contour C, \Rightarrow

$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 I$$

becomes convenient to determine \overline{B}

If the charge distribution has certain symmetry, s.t. the normal component of \vec{E} is constant over a Gaussian surface S, \Rightarrow $\oint_{S} \vec{E} \cdot d\vec{s} = Q/\varepsilon_{0}$ becomes convenient to get \vec{E} Example 11-1: Long conducting wire (1)

Consider an infinitely long conducting wire with circular cross section, and carrying a steady current *I*. Find \overline{B}



Cylindrical symmetry:

 $\vec{B} = \begin{cases} \vec{a}_{\phi} B_{\phi 1}(r), \text{ if } r < b \\ \vec{a}_{\phi} B_{\phi 2}(r), \text{ if } r > b \end{cases}$

Choose a concentric circle of radius *r* as the integral path Example 11-1: Long conducting wire (2)

(1) For
$$r < b$$
:

$$\oint_{C_1} \vec{B} \cdot d\vec{l} = 2\pi r B_{\phi 1}(r) = \mu_0 \left(\frac{r}{b}\right)^2 \vec{I}$$

$$\Rightarrow B_{\phi 1}(r) = \frac{\mu_0 I}{2\pi b^2} r$$

(2) For
$$r > b$$
:

$$\oint_{C_2} \vec{B} \cdot d\vec{l} = 2\pi r B_{\phi 2}(r) = \mu_0 I$$
$$\Rightarrow B_{\phi 2}(r) = \frac{\mu_0 I}{2\pi r}$$



Example 11-2: Solenoid

Consider an infinitely long solenoid with air core, *n* turns per unit length, carrying a steady current *I*. Find \overline{B} inside the solenoid

$$\vec{B} = 0 \text{ outside}$$

$$\vec{B} = \vec{a}_z B \text{ inside}$$

$$\vec{B} = \vec{a}_z B \text{ inside}$$

$$\vec{A} = \vec{A}_z B \text{ inside}$$



- 1. Definition
- 2. Vector Poisson equation
- 3. Vector magnetic potential due to current distributions
- 4. Finite current-carrying wires

Definition

be.

$$\begin{cases} \nabla \cdot \vec{B} = 0 \\ & \longrightarrow \quad \vec{B} = \nabla \times \vec{A} \\ \nabla \cdot (\nabla \times \vec{A}) = 0 & \text{vector potential} \end{cases}$$

Physical meaning

The flux Φ of \overline{B} over a given area *S* bounded by contour *C* is:

$$\Phi(Wb) = \int_{S} \vec{B} \cdot d\vec{s}$$
$$= \int_{S} (\nabla \times \vec{A}) \cdot d\vec{s} = \oint_{C} \vec{A} \cdot d\vec{l}$$



Poisson's equation-1

 $\begin{cases} \nabla \times \vec{A} = \vec{B} & \text{Need to specify the} \\ & \text{divergence of } \vec{A} & \text{to uniquely} \\ \nabla \cdot \vec{A} = ? & \text{define the vector field } \vec{A} \end{cases}$

In principle, specification of $\nabla \cdot \vec{A}$ is arbitrary (no physical constraint)

In reality, choose $\nabla \cdot \vec{A} = 0$ (Coulomb's gauge) to derive simple formula

Poisson's equation-2

$$\begin{cases} \nabla \cdot \vec{A} = 0 \\ \nabla \times \vec{A} = \vec{B} & \longrightarrow & \nabla^2 \vec{A} \equiv \nabla \left(\nabla \cdot \vec{A} \right) - \nabla \times \nabla \times \vec{A} \\ \nabla \times \vec{B} = \mu_0 \vec{J} & = 0 - \nabla \times \vec{B} = -\mu_0 \vec{J} \end{cases}$$

Vector magnetic potential \overline{A} satisfies vector Poisson's equation:

$$\nabla^2 \vec{A} = -\mu_0 \vec{J}$$

Poisson's equation-3

Scalar electric potential *V* satisfies scalar Poisson's equation:



Evaluation-1

In Cartesian coordinates:

$$\nabla^{2} \vec{A} = -\mu_{0} \vec{J} \quad \dots 1 \text{ vector Poisson's equation}$$

$$\Rightarrow \begin{cases} \vec{a}_{x} (\nabla^{2} A_{x}) + \vec{a}_{y} (\nabla^{2} A_{y}) + \vec{a}_{z} (\nabla^{2} A_{z}) \\ = \vec{a}_{x} (\mu_{0} J_{x}) + \vec{a}_{y} (\mu_{0} J_{y}) + \vec{a}_{z} (\mu_{0} J_{z}) \end{cases}$$

$$\Rightarrow \nabla^2 A_i = -\mu_0 J_i (i = x, y, z)$$

...3 independent scalar Poisson's equations

Evaluation-2

Solution to
$$\nabla^2 V = -\varepsilon_0^{-1} \rho_v$$
 is:

$$V(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \int_{V'} \frac{\rho_v(\vec{r}')}{R(\vec{r},\vec{r}')} dv'$$

find potential by integration of source charge

Solution to $\nabla^2 A_i = -\mu_0 J_i$ is:

$$A_i(\vec{r}) = \frac{\mu_0}{4\pi} \int_{V'} \frac{J_i(\vec{r}')}{R(\vec{r},\vec{r}')} dv'$$

Evaluation-3

Solution to $\nabla^2 \vec{A} = -\mu_0 \vec{J}$ is: $\vec{A} = \vec{a}_x A_x + \vec{a}_y A_y + \vec{a}_z A_z$ $\begin{vmatrix} A_i(\vec{r}) = \frac{\mu_0}{4\pi} \int_{V'} \frac{J_i(\vec{r}')}{R(\vec{r},\vec{r}')} dv' \end{vmatrix}$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int_{V'} \frac{\vec{J}(\vec{r}')}{R(\vec{r},\vec{r}')} dv'$$

find potential by integration of source current

Find \overline{A} and \overline{B} in the bisecting plane (z=0) due to a straight wire of length 2L carrying current I:



In cylindrical coordinates:

$$\vec{r} = (r, \phi, 0) = \vec{a}_r r$$

$$0 \sim 2\pi$$

$$\vec{r}' = (0, \phi, \underline{z'}) = \vec{a}_z z'$$
$$-L \sim L$$

$$R(\vec{r}, \vec{r}') = |\vec{r} - \vec{r}'| = \sqrt{r^2 + {z'}^2}$$

$$\vec{J}(\vec{r}') = \vec{a}_z \frac{I}{S}, \quad dv' = Sdz'$$

Example 11-3: Finite current-carrying wire (2)

By
$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int_{V'} \frac{\vec{J}(\vec{r}')dv'}{R(\vec{r},\vec{r}')} \rightarrow \vec{a}_z Idz'$$

 $\vec{A}(r,\phi,z=0) = \vec{a}_z \frac{\mu_0 I}{4\pi} \left(\int_{-L}^{L} \frac{dz'}{\sqrt{r^2 + z'^2}} \right)$
 $= \vec{a}_z \frac{\mu_0 I}{2\pi} \ln \left[\frac{1 + \sqrt{1 + (r/L)^2}}{(r/L)} \right]$

 $A_z(r,\phi,z=0)$

Example 11-3: Finite current-carrying wire (3)



Comment

1. Since
$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int_{V'} \frac{\vec{J}(\vec{r}')dv'}{R(\vec{r},\vec{r}')}$$
 is also a vector integral, determine \vec{B} by way of \vec{A} is less helpful (vs. determine \vec{E} by *V*)

2.
$$\vec{B}(r,\phi,0) \rightarrow \vec{a}_{\phi} \frac{\mu_0 I}{2\pi r}$$
 if $r \ll L$



- 1. Magnetic field due to current loops
- 2. On-axis magnetic field due to a circular current loop

For a closed loop C' carrying a current I, \Rightarrow



Proof:

(1)
$$\vec{A}(\vec{r}) = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}'}{R(\vec{r},\vec{r}')}, \implies \vec{B} = \nabla \times \vec{A}$$

$$= \frac{\mu_0 I}{4\pi} \nabla \times \left[\oint_{C'} \frac{d\vec{l}'}{R(\vec{r},\vec{r}')} \right] = \frac{\mu_0 I}{4\pi} \oint_{C'} \nabla \times \left[\frac{d\vec{l}'}{R(\vec{r},\vec{r}')} \right]$$

(2) $\nabla \times \left(R^{-1} d\vec{l}' \right) = R^{-1} \left(\nabla \times d\vec{l}' \right) + \nabla \left(R^{-1} \right) \times d\vec{l}'$



$$\vec{B} = \frac{\mu_0 I}{4\pi} \oint_C \nabla \times \left[\frac{d\vec{l}'}{R(\vec{r},\vec{r}')} \right] - \vec{a}_R R^{-2}$$
$$= R^{-1} \left(\nabla \times d\vec{l}' \right) + \nabla \left(R^{-1} \right) \times d\vec{l}'$$

$$\Rightarrow \vec{B} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{-\vec{a}_R \times d\vec{l'}}{R^2} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l'} \times \vec{a}_R}{R^2}$$

...Biot-Savart law

Comment

$$\overline{\vec{B}} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l'} \times \vec{a}_R}{R^2} \dots \text{Biot-Savart law}$$

Directly find magnetic field from current distribution without first calculating vector potential \vec{A}

$$\left| \vec{E}(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \int_{V'} \vec{a}_R \frac{\rho_v(\vec{r}')}{R^2} dv' \right| \dots \text{Coulomb's law}$$

Directly find electric field from charge distribution without first calculating scalar potential *V*

Example 11-4: Circular current-carrying loop (1)

Find \overline{B} on the *z*-axis due to a circular loop of radius *b* carrying current *I*:



Example 11-4: Circular current-carrying loop (2)



Example 11-4: Circular current-carrying loop (3)

$$\vec{B}(0,0,z) = \vec{a}_z \frac{\mu_0 I}{2b} \left[1 + (z/b)^2 \right]^{-3/2}$$





- 1. Definition
- 2. Distant magnetic vector potential due to a dipole
- 3. Distant magnetic field due to a dipole

Definition

Essential in modeling the interaction between magnetic materials and external magnetic field (Lesson 12)





Far magnetic field-2

$$\begin{split} \bar{R}_{1} &= R\bar{a}_{R}(\theta, \pi/2) - b\bar{a}_{R}'(\pi/2, \phi') \\ \Rightarrow R_{1}^{2} &= \left(\bar{R}_{1} \cdot \bar{R}_{1}\right) = R^{2} + b^{2} - 2Rb\left(\bar{a}_{R} \cdot \bar{a}_{R}'\right) \\ \xrightarrow{P(R, \theta, \pi/2)} &\cos \psi = \left(\bar{a}_{y} \sin \theta + \bar{a}_{z} \cos \theta\right) \\ \cdot \left(\bar{a}_{x} \cos \phi' + \bar{a}_{y} \sin \phi'\right) = \sin \theta \sin \phi' \\ \cdot \left(\bar{a}_{x} \cos \phi' + \bar{a}_{y} \sin \phi'\right) = \sin \theta \sin \phi' \\ R_{1}^{-1} &= \left\{\left(R^{2} + b^{2} - 2Rb \sin \theta \sin \phi'\right)^{-1/2} \\ &= \left\{\left(R^{2} \left[1 + \left(\frac{b}{R}\right)^{2} - \frac{2b}{R} \sin \theta \sin \phi'\right]\right\}^{-1/2} \\ &= \left\{\left(R^{2} \left[1 + \frac{b}{R} \sin \theta \sin \phi'\right]\right\}^{-1/2} \\ \approx \frac{1}{R} \left(1 + \frac{b}{R} \sin \theta \sin \phi'\right), \text{ if } R >> b \end{split}$$

Far magnetic field-3



$$d\vec{l}' = \vec{a}_{\phi}' b d\phi' = b d\phi' \left(-\vec{a}_x \sin \phi' + \vec{a}_y \cos \phi' \right)$$

Far magnetic field-4

$$\vec{A}(\vec{r}) \approx \frac{\mu_0 I b}{4\pi R} \left[-\vec{a}_x \int_0^{2\pi} \left(\sin \phi' + \frac{b}{R} \sin \theta \sin^2 \phi' \right) d\phi' + \vec{a}_y \int_0^{2\pi} \left(\cos \phi' + \frac{b}{R} \sin \theta \sin \phi' \cos \phi' \right) d\phi' \right]$$

$$= \frac{\mu_0 I b}{4\pi R} \left(-\vec{a}_x \frac{b}{R} \sin \theta \cdot \pi \right) = -\vec{a}_x \frac{\mu_0 I \pi b^2 \sin \theta}{4\pi R^2}$$

Far magnetic field-5

$$\vec{m} \times \vec{a}_{R}(\theta, \pi/2) = \left(\underline{\vec{a}_{z}}I\pi b^{2}\right) \times \left(\underline{\vec{a}_{y}}\sin\theta + \overline{\vec{a}_{z}}\cos\theta\right)$$

$$= -\vec{a}_{x}I\pi b^{2}\sin\theta$$

$$\vec{A}(\vec{r}) = \vec{a}_{\phi}A_{\phi}$$

$$\vec{A}(\vec{r}) = -\vec{a}_{x}\frac{\mu_{0}I\pi b^{2}\sin\theta}{4\pi R^{2}}$$

$$\Rightarrow \vec{A}(\vec{r}) = \frac{\mu_{0}\vec{m} \times \vec{a}_{R}}{4\pi R^{2}}$$

$$\Rightarrow \vec{A}(\vec{r}) = \vec{a}_{\phi}A_{\phi}, A_{\phi}(R,\theta) = \frac{\mu_{0}m\sin\theta}{4\pi R^{2}}$$

Far magnetic field-6

$$\begin{aligned}
A_{\phi}(R,\theta) &= \frac{\mu_0 m \sin \theta}{4\pi R^2} \\
\bar{B}(\bar{r}) &= \nabla \times \left(\bar{a}_{\phi} A_{\phi}\right) \approx \bar{a}_R \frac{1}{R \sin \theta} \frac{\partial}{\partial \theta} \left(A_{\phi} \sin \theta\right) - \bar{a}_{\theta} \frac{1}{R} \frac{\partial}{\partial R} \left(A_{\phi} R\right) \\
&\left\{ \frac{\partial}{\partial \theta} \left(A_{\phi} \sin \theta\right) &= \frac{\mu_0 m}{4\pi R^2} \frac{\partial}{\partial \theta} \left(\sin^2 \theta\right) &= \frac{\mu_0 m}{4\pi R^2} \sin 2\theta \\
&\frac{\partial}{\partial R} \left(A_{\phi} R\right) &= \frac{\mu_0 m \sin \theta}{4\pi} \frac{\partial}{\partial R} \left(\frac{1}{R}\right) &= -\frac{\mu_0 m \sin \theta}{4\pi R^2} \\
\bar{B}(\bar{r}) &\approx \bar{a}_R \frac{1}{R \sin \theta} \frac{\mu_0 m}{4\pi R^2} \sin 2\theta + \bar{a}_{\theta} \frac{1}{R} \frac{\mu_0 m \sin \theta}{4\pi R^2} \\
&\bar{B}(\bar{r}) \approx \frac{\mu_0 m}{4\pi R^3} \left[\bar{a}_R 2 \cos \theta + \bar{a}_{\theta} \sin \theta\right]
\end{aligned}$$

Comment-1



Comment-2

