

Lesson 2 Transmission Lines Fundamentals

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- Current electronic technology is based on lumped circuit theory (simple, powerful):
- 1. Lumped elements (R, C, L, dependent sources) are connected in series or shunt
- 2. Conducting wires play no role



Why to discuss transmission lines-2

In fact, elements and wires provide a framework over which electric charges can move and set up the (total) EM vector fields. The behavior of circuit is thus determined.



- Distributed circuit (transmission lines) theory is somewhere in between:
- 1. Can describe some wave properties (wavelength, phase velocity, reflection, ...), which are crucial in power transmission, high-speed IC,
- 2. Only deal with scalar quantities (*v*, *i*), require no complicated vector analysis



Criteria of using distributed circuits

• Finite speed of propagation v = c/n



Example 2-1: Power lines



Lumped circuit is inadequate when $t_d > 0.01T$ (rule of thumb), $\Rightarrow l > 50 \text{ km}$

Example 2-2: Interconnection of ICs

1-cm silica interconnection



Lumped circuit is inadequate when $t_r < 2.5t_d \approx 165 \text{ ps}$ (rule of thumb). Fast CMOS can have $t_r \approx 100 \text{ ps}$! Background knowledge-1

Models of linear circuit elements:



Background knowledge-2

Kirchhoff's laws :



$$\sum_{k} v_{k} = 0$$

Background knowledge-3

Phasors of sinusoidal functions:

$$v(t) = V_0 \cos(\omega t + \phi) = \operatorname{Re} \left(V e^{j\omega t} \right)$$
$$V = V_0 e^{j\phi} = V_0 \left(\cos \phi + j \sin \phi \right)$$

$$\frac{d}{dt}v(t) = \operatorname{Re}\left\{V \cdot \frac{d}{dt}e^{j\omega t}\right\} = \operatorname{Re}\left\{j\omega V\right\}e^{j\omega t}$$

 $\frac{d^n}{dt^n} \rightarrow (j\omega)^n \quad \text{Derivatives} \rightarrow \text{Algebraic multiplication}$



Sec. 2-2 Equivalent Circuit and Equations of Transmission Lines

- 1. Geometry of typical TX lines
- 2. Equivalent circuit
- 3. TX line equations
- 4. Solutions

Geometry of typical transmission lines



- Two long conductors, separated by some insulating material
- $v(z_0,t)$ across, $\pm i(z_0,t)$ along the conductors

Since the voltage, current can vary with z, \Rightarrow use of distributed circuit model, i.e. a TX line consists of infinitely many coupled lines of infinitesimal length Δz



Equivalent circuit-2

- Currents on a short line set up magnetic field (Ampere's law), ⇒ magnetic flux
- Time-varying current (flux), ⇒ voltage changes along the line (Faraday's law) to counter the change of current (Lenz's law), ⇒ series inductor





■ The upper and lower conductors of the adjacent short lines are connected respectively, ⇒ shunt capacitor



Equivalent circuit-4

- Imperfect conducting materials, \Rightarrow voltage drop along the conducting line, \Rightarrow series resistor
- Imperfect insulating materials, \Rightarrow leakage current between conductors, \Rightarrow shunt conductor



Complete model: {R, L, G, C} as {resistance, inductance, conductance, capacitance} per unit length



- By the equivalent circuit, the behavior of vector EM fields can be described by scalar voltage and current.
- Values of R, L, G, C depend on the geometry and materials of the transmission line.

• Assume R=0, G=0: by KVL



$$v(z + \Delta z, t) = v(z, t) - (L\Delta z) \frac{\partial}{\partial t} i(z, t)$$

$$\Rightarrow v(z + \Delta z, t) - v(z, t) = -(L\Delta z)\frac{\partial}{\partial t}i(z, t)$$

$$\Rightarrow \frac{v(z + \Delta z, t) - v(z, t)}{\Delta z} = -(L) \frac{\partial}{\partial t} i(z, t)$$

Let $\Delta z \rightarrow 0$,

$$\Rightarrow \frac{\partial}{\partial z} v(z,t) = -L \frac{\partial}{\partial t} i(z,t)$$
 (2.1)

1st-order PDE with **2** unknown functions *v* and *i*



$$i(z,t) = i(z + \Delta z, t) + (C\Delta z)\frac{\partial}{\partial t}v(z + \Delta z, t)$$

$$\Rightarrow i(z,t) - i(z + \Delta z, t) = (C\Delta z)\frac{\partial}{\partial t}v(z + \Delta z, t)$$

$$\Rightarrow \frac{i(z,t) - i(z + \Delta z, t)}{\Delta z} = (C)\frac{\partial}{\partial t}v(z + \Delta z, t)$$

Let $\Delta z \rightarrow 0$,

$$\Rightarrow \boxed{\frac{\partial}{\partial z}i(z,t) = -C\frac{\partial}{\partial t}v(z,t)}$$
(2.2)

1st-order PDE with 2 unknown functions *v* and *i*

Taking
$$\frac{\partial}{\partial z}$$
 for both sides of eq. (2.1),
 $\frac{\partial}{\partial z}v(z,t) = -L\frac{\partial}{\partial t}i(z,t), \Rightarrow \frac{\partial^2}{\partial z^2}v(z,t) = -L\frac{\partial^2}{\partial z\partial t}i(z,t)$

Taking
$$\frac{\partial}{\partial t}$$
 for both sides of eq. (2.2),
 $\frac{\partial}{\partial z}i(z,t) = -C\frac{\partial}{\partial t}v(z,t), \Rightarrow \overbrace{\partial z\partial t}^{2}i(z,t) = -C\frac{\partial^{2}}{\partial t^{2}}v(z,t)$

Combine the two equations:

$$\Rightarrow \frac{\partial^2}{\partial z^2} v(z,t) = LC \frac{\partial^2}{\partial t^2} v(z,t)$$

2nd-order PDE with **1** unknown function *v*

$$\frac{\partial^2}{\partial z^2} v(z,t) = LC \frac{\partial^2}{\partial t^2} v(z,t) \quad (2.3)$$
$$\frac{\partial^2}{\partial z^2} i(z,t) = LC \frac{\partial^2}{\partial t^2} i(z,t) \quad (2.4)$$



D'Alembart's solution to wave equation: any function $f(\cdot)$ of variable $\tau = t \pm \frac{z}{v_p}$ $f(t - z/v_p) \sim \text{distortion-free wave traveling in the}$ +z direction with velocity v_p



$f(t + z/v_p) \sim \text{distortion-free wave traveling in the}$ -z direction with velocity v_p

General solution to the voltage (superposition):

$$v(z,t) = (f^{+}(t - z/v_{p}) + (f^{-}(t + z/v_{p}))$$
(2.6)
Can be totally different functions
determined by BCs and ICs.
Their superposition may have "distortion".

Comments

• Phase velocity $v_p = \frac{1}{\sqrt{LC}}$ only depends on

the insulating materials, though *L*, *C* also depend on the geometry of the lines



Substitute voltage solution $v(z,t) = f^+(t-z/v_p) + f^-(t+z/v_p)$ into the 1st-order PDE: $\frac{\partial}{\partial z}v(z,t) = -L\frac{\partial}{\partial t}i(z,t)$

$$\Rightarrow \frac{\partial v}{\partial z} = -\frac{1}{v_p} \frac{df^+(\tau)}{d\tau} + \frac{1}{v_p} \frac{df^-(\tau)}{d\tau} = -L \frac{\partial i}{\partial t}$$
$$\Rightarrow i(z,t) = -\frac{1}{L} \int \frac{\partial v}{\partial z} \partial t = \frac{1}{Lv_p} \int \left[\frac{df^+(\tau)}{d\tau} - \frac{df^-(\tau)}{d\tau} \right] \partial t$$

$$\because \frac{\partial \tau}{\partial t} = 1, \Rightarrow i(z,t) = \sqrt{\frac{C}{L}} \int \left[\frac{df^+(\tau)}{d\tau} - \frac{df^-(\tau)}{d\tau} \right] d\tau$$

$$v(z,t) = f^{+}(t - z/v_{p}) + f^{-}(t + z/v_{p}) = v^{+}(z,t) + v^{-}(z,t)$$

$$\Rightarrow i(z,t) = \frac{1}{Z_0} \Big[f^+ \Big(t - z / v_p \Big) - f^- \Big(t + z / v_p \Big) \Big] = i^+ (z,t) + i^- (z,t)$$

 $Z_0 = \sqrt{\frac{L}{C}}$ Characteristic impedance (not the resistance of the conductor or insulator)

$$Z_0 = \frac{v^+(z,t)}{i^+(z,t)} = -\frac{v^-(z,t)}{i^-(z,t)} \neq \frac{v(z,t)}{i(z,t)}$$
 Physical meaning

Example 2-3:

Infinitely long line, no reflected wave $v^{-}(z,t)$ TX line ~ a load of resistance $Z_0 = \sqrt{\frac{L}{C}}$ $i_s(t)$ $v^+(z,t=t_0)$ V_0 V_s R_s $v_s(t)$ Z_0 (z,t) $\rightarrow V_p$ V_0 Z0 $v_p t_0$ z=0

$$v_s(t=0^+) = V_s = \frac{Z_0}{Z_0 + R_s} V_0$$