

Lesson 09 Complex Numbers and Functions (EK 13)

■ Overview

Contents: complex numbers, analytic functions, complex series, complex integral.

Applications:

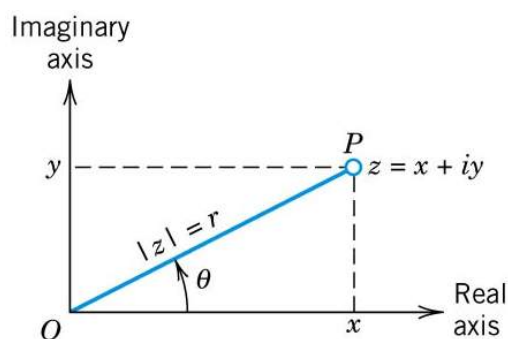
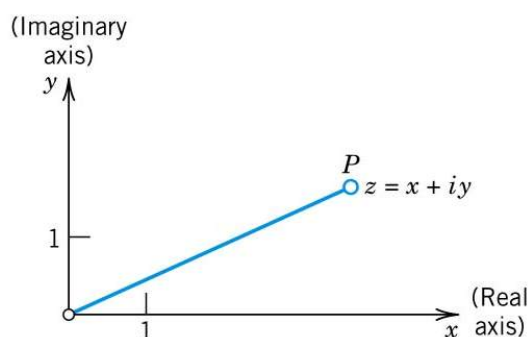
- 1) Evaluate complicated real and complex integrals (EK 16).
- 2) Derive Fourier and Laplace transforms in closed form.
- 3) Solve 2-D Laplace's equation (EK 17, 18).

Complex Numbers (EK13.1-2)

■ Representations

- 1) Cartesian form: $z=x+iy$, where $x=\text{Re}\{z\}$, $y=\text{Im}\{z\}$, $i=\sqrt{-1}$; a point in the complex plane.
- 2) Polar form: $z=re^{i\theta}$, where $r=|z|=\sqrt{x^2+y^2}$ = **modulus** of z , $\theta=\text{Arg}(z)=\tan^{-1}\left(\frac{y}{x}\right)=$

argument (幅角) of z . Since \tan^{-1} gives values between $-\frac{\pi}{2}$ and $\frac{\pi}{2}$ (I and IV quadrants), $\tan^{-1}\left(\frac{y}{x}\right)$ cannot tell the arguments of z and $-z$, $\Rightarrow \theta=\tan^{-1}\left(\frac{y}{x}\right)+\pi$, if $x<0$.



■ Properties

- 1) Addition/subtraction: Cartesian form is preferable. $z_1 \pm z_2 = (x_1 \pm x_2) + i(y_1 \pm y_2)$.
- 2) Multiplication/division: Polar form is preferable. $z_1 z_2 = (r_1 r_2) e^{i(\theta_1 + \theta_2)}$, $\frac{z_1}{z_2} = \frac{r_1}{r_2} e^{i(\theta_1 - \theta_2)}$.
- 3) Complex conjugate: $z^* = (x - iy) = r e^{-i\theta}$. The conjugate pairs z and z^* can be used to express parameters in Cartesian and polar forms:

$$x = \frac{z + z^*}{2}, y = \frac{z - z^*}{2i}, r = \sqrt{z \cdot z^*}, \theta = \frac{1}{2} \text{Arg} \left(\frac{z}{z^*} \right).$$

- 4) Integral powers: $z^n = r^n e^{in\theta}$ (proved by induction).

Applications: expressing $\cos(n\theta)$, $\sin(n\theta)$ in terms of powers of $\cos\theta$, $\sin\theta$.

E.g. $\cos(2\theta) = \text{Re}\{e^{i2\theta}\} = \text{Re}\{(\cos\theta + i\sin\theta)^2\} = \cos^2\theta - \sin^2\theta$.

- 5) Integral roots: $\sqrt[n]{z} = \sqrt[n]{r} \exp\left[i\frac{\theta + 2k\pi}{n}\right]$, $k=0, 1, \dots, n-1$ (multivalued function).

Proof: Let $z = r e^{i\theta}$, $w = R e^{i\phi} = \sqrt[n]{z} \Rightarrow w^n = z$, $R^n e^{in\phi} = r e^{i\theta}$, $R = \sqrt[n]{r}$, $\phi = \frac{\theta + 2k\pi}{n}$, $k=0, \dots, n-1$.

Analytic Functions (EK13.3)

■ Sets in the complex plane

- 1) Neighborhood of a : $\{z, |z - a| < \rho\}$ (open circular disk).
- 2) Open set S : every point of S has a neighborhood only consisting of points belonging to S .

E.g. $|z| < 1$ is open, $|z| \leq 1$ is not open.

- 3) Connected set S : any two of its points can be joined by a broken line (linear segments) within S . **E.g.** $\{|z| < 1 \text{ and } |z - 3| < 1\}$ is NOT connected.

- 4) **Domain**: an open connected set.

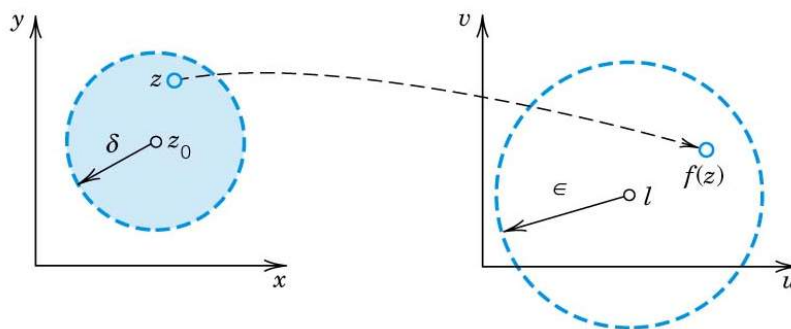
■ Complex functions

$w = f(z = x + iy) = u(x, y) + iv(x, y)$. A complex function w of single complex variable z is equivalent

to a pair of real functions $u(x,y)$ and $v(x,y)$, each depending on two real variables x, y .

■ Limit

$\lim_{z \rightarrow z_0} f(z) = l$: for every real $\epsilon > 0$, we can find a real $\delta > 0$, such that $|f(z) - l| < \epsilon$ if $0 < |z - z_0| < \delta$.



Unlike the limit of real functions: $\lim_{x \rightarrow x_0} f(x) = l$, where x can only approach x_0 from left and right hand sides (1-D); z can approach z_0 from infinitely many directions in the complex plane (2-D, draw a plot). The limit exists only if $f(z)$ approaches the same l from all possible paths.

■ Continuous

A function $f(z)$ is continuous at $z = z_0$, if $\lim_{z \rightarrow z_0} f(z) = f(z_0)$.

■ Derivative

$f(z)$ is **differentiable** at z_0 , if the derivative (limit of difference quotient):

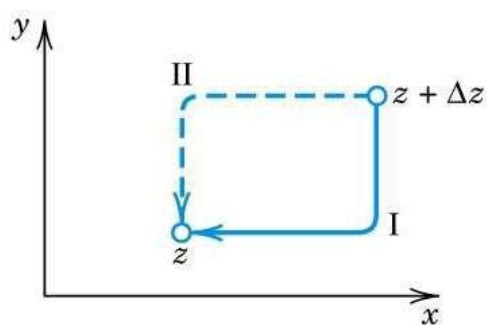
$$f'(z_0) = \lim_{\Delta z \rightarrow 0} \frac{f(z_0 + \Delta z) - f(z_0)}{\Delta z} \tag{9.1}$$

approaches the same value as $\Delta z \rightarrow 0$ along all paths.

E.g. $f(z) = z^2$. $f'(z) = \lim_{\Delta z \rightarrow 0} \frac{(z + \Delta z)^2 - z^2}{\Delta z} = \lim_{\Delta z \rightarrow 0} \frac{2z(\Delta z) + (\Delta z)^2}{\Delta z} = 2z$, for all $z \in C$.

E.g. $f(z) = z^*$. $f'(z) = \lim_{\Delta z \rightarrow 0} \frac{(z + \Delta z)^* - z^*}{\Delta z} = \lim_{\Delta z \rightarrow 0} \frac{(\Delta z)^*}{\Delta z} = \lim_{\Delta z \rightarrow 0} \frac{\Delta x - i\Delta y}{\Delta x + i\Delta y}$, whose value depends on

the path (see figure below). \Rightarrow The derivative does not exist for **all** $z \in \mathbb{C}$. Unlike real functions, differentiability is a rather strict requirement for complex functions.



For path I, $\Delta y=0, \Delta z=\Delta x \rightarrow 0$, causing a limit of +1. For path II, $\Delta x=0, \Delta z=i\Delta y \rightarrow 0$, causing a limit of -1.

Note we cannot let $\Delta x=\Delta y=0$ simultaneously, which violates the definition of “limit”.

$f(z)$ is **analytic** in a domain D , if $f(z)$ is **differentiable** at all points of D . $f(z)$ is analytic at a point z_0 , if $f(z)$ is analytic in a neighborhood of z_0 .

Cauchy-Riemann (CR) Equations (EK13.4)

■ $f(z=x+iy)=u(x,y)+iv(x,y)$ is analytic \Leftrightarrow CR equations are satisfied:

$$\{u_x = v_y, \quad u_y = -v_x\} \tag{9.2}$$

Proof (\Rightarrow): Analytic \Rightarrow differentiable, $f'(z) = \lim_{\Delta z \rightarrow 0} \frac{f(z + \Delta z) - f(z)}{\Delta z}$ has the same value for

all possible paths $\Delta z \rightarrow 0$. We examine the two special paths I and II illustrated above:

(i) For path I, $\Delta z = \Delta x \rightarrow 0, f'(z) = \lim_{\Delta x \rightarrow 0} \frac{[u(x + \Delta x, y) + iv(x + \Delta x, y)] - [u(x, y) + iv(x, y)]}{\Delta x} =$

$u_x + iv_x$. (ii) For path II, $\Delta z = i\Delta y \rightarrow 0, \Rightarrow f'(z) = v_y - iu_y$. Equating their real and imaginary parts gives rise to eq. (9.2).

E.g. $f(z)=z^*=(x-iy), \{u=x, v=-y\}; u_x=1 \neq v_y=-1, \Rightarrow f(z)=z^*$ is not analytic.

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The relations derived during the proof of CR equations:

$$f'(z) = u_x + iv_x = v_y - iu_y \tag{9.3}$$

can be used to evaluate complex derivative.

■ Real and imaginary parts of an analytic function satisfy 2-D Laplace's equation.

Proof: $f(z)=u(x,y)+iv(x,y)$ is analytic, by eq. (9.2), $\Rightarrow \{u_x=v_y, u_y=-v_x\}$. $\Rightarrow \{u_{xx}=v_{yx}, u_{yy}=-v_{xy}\}$;

$u_{xx}+u_{yy}=\nabla^2 u=0$; Similarly, $\nabla^2 v=0$.

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$\nabla^2 u=0, \nabla^2 v=0$ does not guarantee that $f(z)=u(x,y)+iv(x,y)$ is analytic.

Exponential Function (EK13.5)

■ Definition:

$$e^z \equiv e^x(\cos y + i \sin y), \text{ or } \sum_{n=0}^{\infty} z^n/n! \quad (9.4)$$

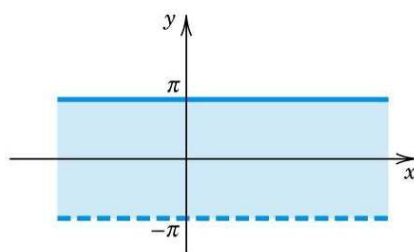
■ Properties:

1) e^z is analytic for all z . Proof: $u=e^x \cdot \cos(y), v=e^x \cdot \sin(y)$, by eq. (9.2),

2) $\frac{d}{dz} e^z = e^z$. Proof: by eq. (9.3), $\frac{d}{dz} e^z = u_x + iv_x = u + iv = e^z$.

3) $e^{z_1+z_2} = e^{z_1} \cdot e^{z_2}$. Proof: let $z_1=x_1+iy_1, z_2=x_2+iy_2$, apply $e^{x_1+x_2} = e^{x_1} e^{x_2}$ and trigonometric equalities,

4) $e^{z+i2n\pi} = e^z$, hence the fundamental strip ($x, -\pi < y \leq \pi$) is mapped onto the entire w -plane.



5) The left half-plane $\{x \leq 0\}$ is mapped onto the unit circle in the w -plane.

Trigonometric Functions (EK13.6)

■ Definition:

$$\cos z \equiv \frac{e^{iz} + e^{-iz}}{2}, \quad \sin z \equiv \frac{e^{iz} - e^{-iz}}{2i}, \quad \tan z \equiv \frac{\sin z}{\cos z} \quad (9.5)$$

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Real functions $\sin x$, $\cos x$ are unrelated to real function e^x .

■ Properties:

- 1) $\cos z$, $\sin z$ are analytic for all z , but $(\tan z)$ is not wherever $\cos z = 0$.
- 2) $\cos z = (\cos x \cdot \cosh y) - i(\sin x \cdot \sinh y)$, $\sin z = (\sin x \cdot \cosh y) + i(\cos x \cdot \sinh y)$. Proof: by $\cos z = \frac{1}{2}[e^{i(x+iy)} + e^{-i(x+iy)}] = \dots$
- 3) $|\cos z|^2 = \cos^2 x + \sinh^2 y$, $|\sin z|^2 = \sin^2 x + \sinh^2 y$, not bounded by 1.
Proof: by $|\cos z|^2 = (\cos x \cdot \cosh y)^2 + (\sin x \cdot \sinh y)^2$; $\cosh^2 y = 1 + \sinh^2 y$, $\Rightarrow |\cos z|^2 = \cos^2 x (1 + \sinh^2 y) + \sin^2 x \cdot \sinh^2 y = \dots$
- 4) $\cos z = 0$, for $z = \frac{2n+1}{2}\pi$; $\sin z = 0$, for $z = n\pi$. Proof: by property 2.
- 5) $\frac{d}{dz} \cos z = -\sin z$, $\frac{d}{dz} \sin z = \cos z$. Proof: by eq. (9.5) and $\frac{d}{dz} e^z = e^z$.
- 6) General formulas of real trigonometric functions remain valid for complex counterparts.

Logarithm Function (EK13.7)

■ Definition:

Inverse of exponential function. $w = \ln z \Leftrightarrow z = e^w$. Let $z = re^{i\theta}$, $w = u + iv$, $\Rightarrow re^{i\theta} = e^{u+iv} = e^u e^{iv}$, $\Rightarrow e^u = r$, $v = \theta + 2n\pi$. \Rightarrow

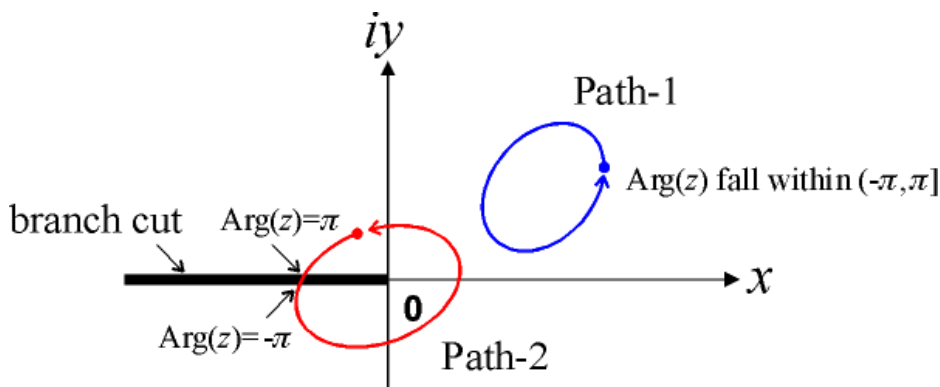
$$\ln z = \ln r + i(\theta + 2n\pi) \quad (9.6)$$

which is a **multi-valued** “function” [i.e. $re^{i\theta}$ and $re^{i(\theta+2n\pi)}$ represent the same point in the z -plane, but are mapped onto different points in the w -plane. Strictly speaking, it is not a function]. **E.g.** $\ln(i)=\ln(1)+i(0.5+2n)\pi$.

The principal value of $\ln z$ is defined as:

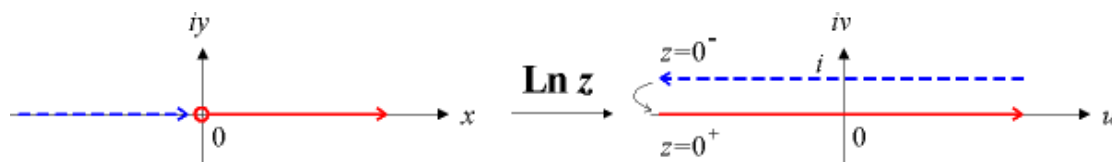
$$\text{Ln } z = \ln|z| + i \text{Arg}(z), \quad -\pi < \text{Arg}(z) \leq \pi \tag{9.7}$$

Though $(\text{Ln } z)$ is single-valued, the restriction of argument $[-\pi < \text{Arg}(z) \leq \pi]$ makes the function **discontinuous** (and non-analytic) when the variable z passes through a branch cut (negative real axis).



■ Properties:

- 1) If z is negatively real (where real logarithm is undefined), $\text{Ln } z = \ln|z| + i\pi$.



- 2) The branch cut of $(\text{Ln } z)$ depends on the choice of argument range.

E.g. if $0 \leq \text{Arg}(z) < 2\pi$ is used, branch cut becomes the positive real axis. In this case, $(\text{Ln } z)$ is continuous and analytic on the negative real axis.

$$3) \ln(z_1 z_2) = \ln z_1 + \ln z_2, \quad \ln\left(\frac{z_1}{z_2}\right) = \ln z_1 - \ln z_2. \quad \text{Proof: by } z_1 = r_1 e^{i\theta_1}, \dots$$

$$4) \frac{d}{dz} \text{Ln } z = \frac{1}{z}, \quad \text{except for points on the branch cut. Proof: by } u = \text{Ln}|z| = \frac{1}{2} \ln(x^2 + y^2),$$

$$v = \text{Arg}\{z\} = \begin{cases} \tan^{-1}(y/x), & \text{if } x \geq 0 \\ \tan^{-1}(y/x) + \pi, & \text{if } x < 0 \end{cases}; \quad \text{by eq. (9.3), } \frac{d}{dz} \text{Ln } z = u_x + i v_x = \frac{x - iy}{x^2 + y^2} = \frac{1}{z}.$$

5) General powers:

$$z^c = e^{c \ln z}; \quad a^z = e^{z \ln a} \quad (9.8)$$

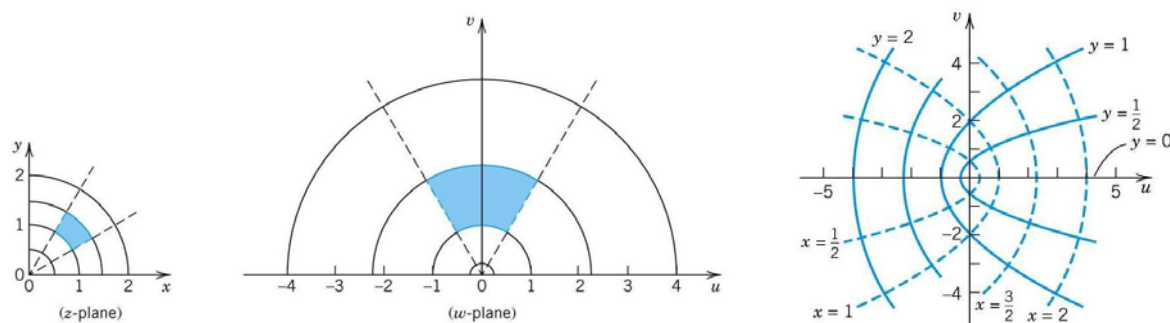
E.g. $i^i = e^{i \ln i} = e^{i[0 + i(\pi/2 + 2n\pi)]} = e^{-(\pi/2 + 2n\pi)} \in \mathbb{R}.$

Appendix 9A – Conformal Mapping (EK 17)

■ Mapping

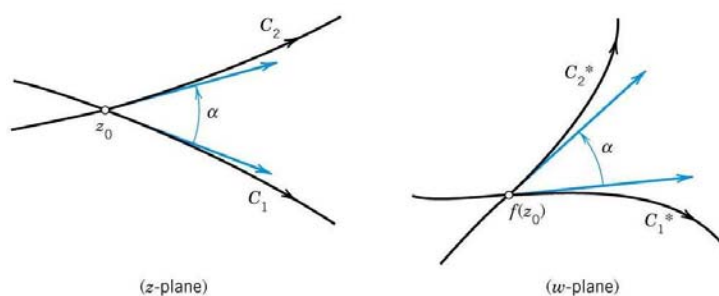
For each point z in the domain of definition D , function $f(z)$ assigns a point $f(z)$ (image of z) in the w -plane, $\Rightarrow f$ defines a mapping of D in the z -plane onto the w -plane.

E.g. $w=z^2$. (i) $Re^{i\phi}=(re^{i\theta})^2=(r^2e^{i2\theta})$, $\Rightarrow \{R=r^2, \phi=2\theta\}$ (lower left figure). (ii) $u+iv=(x+iy)^2 \Rightarrow \{u=x^2-y^2, v=2xy\}$. A vertical line in the xy -plane ($x=x_0$) is mapped onto a parabola in the uv -plane: $u=x_0^2-(v^2/4x_0^2)$. A horizontal line ($y=y_0$) is mapped onto a parabola: $u=(v^2/4y_0^2)-y_0^2$ (lower right figure).



■ Conformal mapping

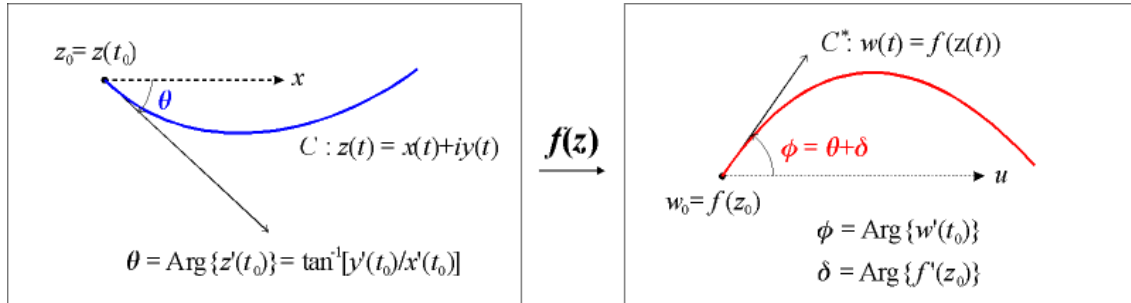
Mapping defined by an analytic function preserves the included angle (夾角, magnitude and sense) between any oriented curves.



Proof: Let curve C in the z -plane have a parametric representation: $z(t)=x(t)+iy(t)$. The tangential at $z=z_0=z(t_0)$ makes an angle θ with respect to the x -axis, where $\tan\theta$

$$= \lim_{\Delta t \rightarrow 0} \frac{\Delta y = y(t_0 + \Delta t) - y(t_0)}{\Delta x = x(t_0 + \Delta t) - x(t_0)} = \lim_{\Delta t \rightarrow 0} \frac{[y(t_0 + \Delta t) - y(t_0)]/\Delta t}{[x(t_0 + \Delta t) - x(t_0)]/\Delta t} = \frac{y'(t_0)}{x'(t_0)}, \text{ i.e.}$$

$$\theta = \text{Arg} \{x'(t_0) + iy'(t_0)\} = \text{Arg} \{z'(t_0)\} \tag{9A.1}$$



Analytic function $f(z)$ maps curve C onto its image $C^* : w(t) = f(z(t)) = u(t) + iv(t)$ in the w -plane.

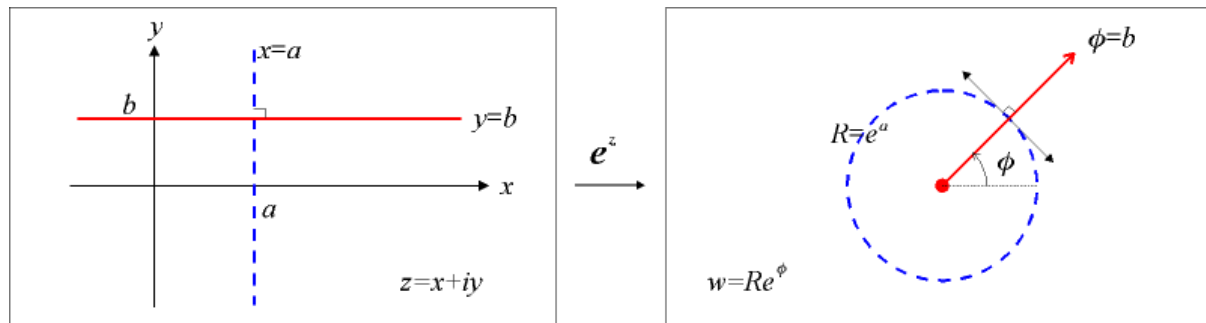
The tangential at $w_0 = f(z_0)$ makes an angle ϕ with respect to the u -axis, where $\phi = \text{Arg} \{w'(t_0)\}$.

By the chain rule, $w'(t_0) = f'(z_0) \cdot z'(t_0) \Rightarrow \text{Arg} \{w'(t_0)\} = \text{Arg} \{f'(z_0)\} + \text{Arg} \{z'(t_0)\}$,

$$\phi = \delta + \theta, \quad \delta = \text{Arg} \{f'(z_0)\} \tag{9A.2}$$

Since δ is only determined by the mapping function, $f(z)$ rotates any oriented curve by the same angle δ , as long as $f'(z_0) \neq 0$ (i.e. $\text{Arg} \{f'(z_0)\}$ exists).

E.g. $f(z) = e^z, z = x + iy; w = Re^{i\phi}, = f(z) = e^{x+iy} = e^x e^{iy}, \Rightarrow \{R = e^x, \phi = y\}$. Vertical line $x = a$ in the z -plane is mapped onto a circle of radius e^a in the w -plane. Horizontal line $y = b$ is mapped onto a ray of angle $\phi = b$. The included angles of $\{x = a, y = b\}$ and $\{R = e^a, \phi = b\}$ are the same (90°).



Conformal mapping is historically important in solving 2-D Laplace's equation. However, it relies on symmetry of the problem, and gives way to the more powerful numerical methods.